

## APPENDIX A

# MATLAB CODE FOR CALCULATION OF MOTOR TORQUE

**Table 1 MATLAB code for calculating motor torque[1]**

```

%Definition of Motor Parameters
V=4000/sqrt(3); %Phase voltage
NoPh=3; %Number of Phase
NoPo=2 %Number of Pole
f=50; %Frequency
R1=0.02; %Stator Resistance
X1=0.01; %Stator Reactance
X2=0.405; %Rotor Reactance
Xm=0.6; %Magnetization Reactance

%Calculation of Synchronous speed
w=4*pi*f/ NoPo;
nSyn=120*f/ NoPo;

%Calculation of Thevenin equivalent circuit
Z1Th=j*Xm*(R1+j*X1)/(R1+j*(X1+Xm));
R1Th=real(Z1Th);
X1Th=imag(Z1Th);
V1Th=(abs(V*j*Xm/(R1+j*(X1+Xm))));

%The loop for Resistance 0.05;0.11;0.2;0.3
for rr=1:4

if rr==1
R2=0.05;
elseif rr==2
R2=0.11;
elseif rr==3
R2=0.2;
else
R2=0.3;
end

%The loop for Slip
for n= 1:200
Slip(n)=n/200;
rpm(n)=nSyn*(1-Slip(n));
I2=abs(V1Th/(Z1Th+j*X2+R2/Slip(n)));
Tor(n)=(NoPh*I2^2*R2/(Slip(n)*w))/1000; %Calculate the mechanical
torque
end

%Plot
plot(rpm,Tor)
if rr==1
hold
end
end
hold
xlabel('Speed [rpm]')
ylabel('Machenical Torque [kN.m]')

```

# APPENDIX B

## MOTOR DATA SHEET

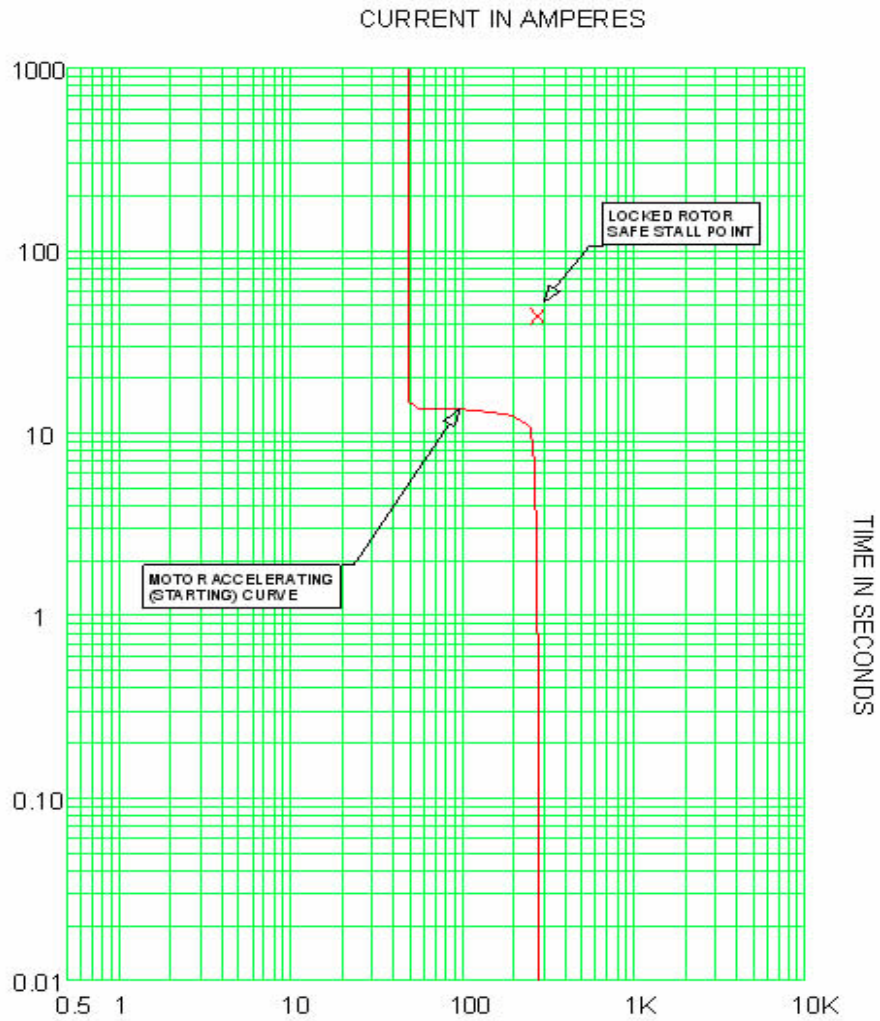


Figure 1 Low voltage induction motor

Table 2 Low voltage induction data sheet

Low Voltage Induction Motor Data		
Rated Horse Power	HP	40 HP
Rated Voltage	Nv	460 V
Number of Pole	#P	4
Full Load Current	FLA	49.4 A
Locked Rotor Current	LRA	275.3 A
Rate Service Factor	SF	1.15
Hot Safe Stall Time at 100% volts		44 sec
Equivalent Circuit Parameters		
Stator Resistance	Rs	0.057 p.u
Stator Reactance	Xs	0.01 p.u
Mag. Reactance	Xm	2.16 p.u
Rotor resistance	Rr	0.03 p.u
Rotor Reactance	Xr	0.22 p.u

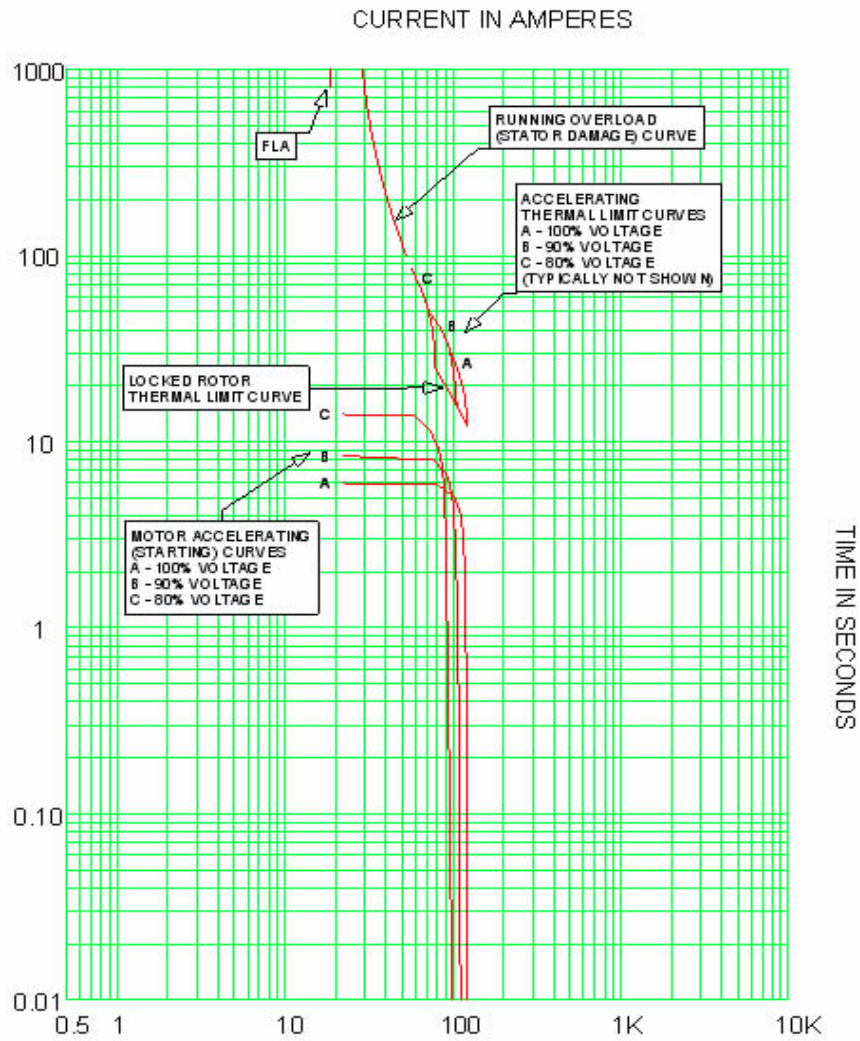


Figure 2 Medium voltage induction motor

Table 3 MV induction motor data sheet

Medium Voltage Induction Motor Data		
Rated Horse Power	HP	1500 HP
Rated Voltage	nV	4000 V
Rated Current	nA	187 A
Number of Pole	#P	2
Equivalent Circuit		
Stator Resistance	Rs	0.02 p.u
Stator Reactance	Xs	0.01 p.u
Mag. Reactance	Xm	0.6 p.u
Rotor resistance	Rr	0.11 p.u
Rotor Reactance	Xr	0.405 p.u

<b>Starting and Thermal Limit Characteristics for MV Induction motor</b>		
<b>Motor Starting Curve</b>	<b>Current (%)</b>	<b>Time(Sec)</b>
<b>Full Load Curve</b>	155	1000
	180	400
	282	100
<b>Rotor Damage Points at 100% Voltage</b>	520	30
	600	25
	660	12
<b>Accelerating Time</b>	<b>Voltage (%)</b>	<b>Time(sec)</b>
	100	6

# APPENDIX C

## SEL701 SETTING DATA SHEET

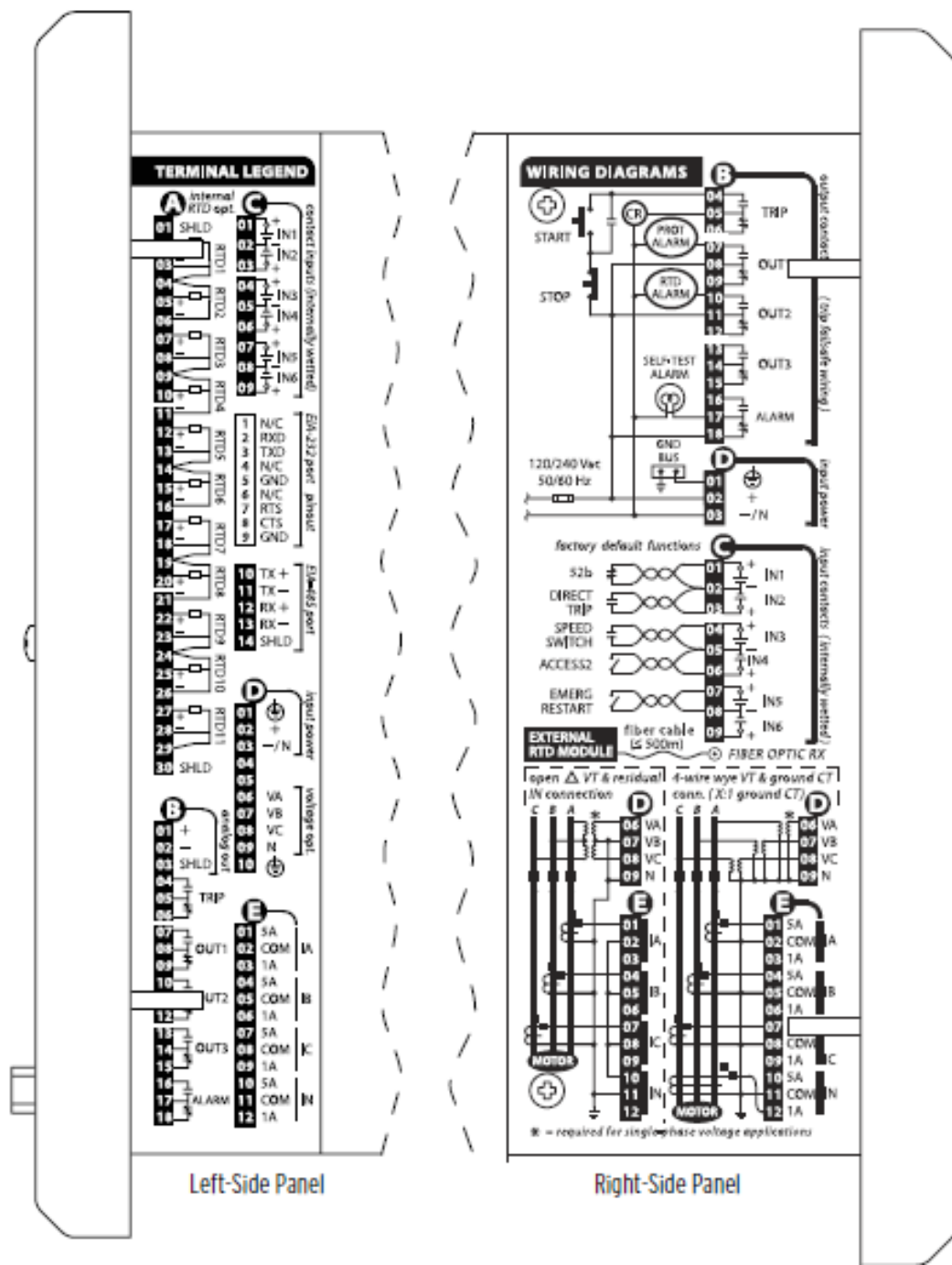


Figure 3 SEL-701 relay left-and right-side panel drawings



**Table 4 Generic Thermal Limit Curve from 1 to 9**

<b>Multiples of full load Amps</b>	<b>Curves</b>								
	<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>	<b>5</b>	<b>6</b>	<b>7</b>	<b>8</b>	<b>9</b>
<b>1.01</b>	311.4	622.7	934.1	1245.4	1556.8	1868.1	2179.5	2490.8	2802.2
<b>1.1</b>	138.9	277.7	416.6	555.4	694.3	833.1	972	1110.8	1249.7
<b>1.15</b>	111.9	223.8	335.7	447.6	559.4	671.3	783.2	895.1	1007
<b>1.2</b>	94	188	282	376	470	564	658	752	846
<b>1.3</b>	71	142	213.1	284.1	355.1	426.1	497.2	568.2	639.2
<b>1.4</b>	56.6	113.2	169.8	226.4	283	339.6	396.2	452.7	509.3
<b>1.5</b>	46.6	93.2	139.8	186.4	233	279.6	326.2	372.8	419.4
<b>1.7</b>	33.7	67.3	101	134.7	168.4	202	235.7	269.4	303
<b>2</b>	22.8	45.6	68.4	91.2	114	136.9	159.7	182.5	205.3
<b>2.5</b>	14.4	28.8	43.2	57.6	72	86.4	100.8	115.2	129.6
<b>3</b>	10	20	30	40	50	60	70	80	90
<b>3.5</b>	7.3	14.7	22	29.4	36.7	44.1	51.4	58.8	66.1
<b>4</b>	5.6	11.2	16.9	22.5	28.1	33.7	39.4	45	50.6
<b>4.5</b>	4.4	8.9	13.3	17.8	22.2	26.7	31.1	35.6	40
<b>5</b>	3.6	7.2	10.8	14.4	18	21.6	25.2	28.8	32.4
<b>6</b>	2.5	5	7.5	10	12.5	15	17.5	20	22.5
<b>7</b>	1.8	3.7	5.5	7.4	9.2	11	12.9	14.7	16.5
<b>8</b>	1.4	2.8	4.2	5.6	7	8.4	9.8	11.3	12.7
<b>9</b>	1.1	2.2	3.3	4.4	5.5	6.6	7.7	8.8	10
<b>10</b>	0.9	1.8	2.7	3.6	4.5	5.4	6.3	7.2	8.1
<b>50</b>	0.9	1.8	2.7	3.6	4.5	5.4	6.3	7.2	8.1

**Table 5 Generic Thermal Limit Curve from 10 to 45**

<b>Multiples of full load Amps</b>	<b>Curves</b>							
	<b>10</b>	<b>15</b>	<b>20</b>	<b>25</b>	<b>30</b>	<b>35</b>	<b>40</b>	<b>45</b>
<b>1.01</b>	3113.6	4670.3	6227.1	7783.9	9340.7	10897.4	12454.2	14011
<b>1.1</b>	1388.5	2082.8	2777.1	3471.3	4165.6	4859.9	5554.1	6248.4
<b>1.15</b>	1118.9	1678.3	2237.8	2797.2	3356.7	3916.1	4475.6	5035
<b>1.2</b>	940	1410.1	1880.1	2350.1	2820.1	3290.2	3760.2	4230.2
<b>1.3</b>	710.2	1065.4	1420.5	1775.6	2130.7	2485.9	2841	3196.1
<b>1.4</b>	565.9	848.9	1131.9	1414.8	1697.8	1980.8	2263.7	2546.7
<b>1.5</b>	466	699.1	932.1	1165.1	1398.1	1631.2	1864.2	2097.2
<b>1.7</b>	336.7	505.1	673.4	841.8	1010.1	1178.5	1346.8	1515.2
<b>2</b>	228.1	342.1	456.2	570.2	684.3	798.3	912.4	1026.4
<b>2.5</b>	144	216	288	360	432	504	576	648
<b>3</b>	100	150	200	250	300	350	400	450
<b>3.5</b>	73.5	110.2	146.9	183.7	220.4	257.1	293.9	330.6
<b>4</b>	56.2	84.4	112.5	140.6	168.7	196.9	225	253.1
<b>4.5</b>	44.4	66.7	88.9	111.1	133.3	155.6	177.8	200
<b>5</b>	36	54	72	90	108	126	144	162
<b>6</b>	25	37.5	50	62.5	75	87.5	100	122.5
<b>7</b>	18.4	27.6	36.8	45.9	55.1	64.3	73.5	82.7
<b>8</b>	14.1	21.1	28.1	35.2	42.2	49.2	56.3	63.3
<b>9</b>	11.1	16.7	22.2	27.8	33.3	38.9	44.4	50
<b>10</b>	9	13.5	18	22.5	27	31.5	36	40.5
<b>50</b>	9	13.5	18	22.5	27	31.5	36	40.5

# APPENDIX D

## MODELLING OF SEL701 RELAY

## 1. Introduction

The *DigSILENT PowerFactory* model of the SEL701 provides the following 'Protection Elements':

- Thermal Overload Protection Element 49
- Instantaneous Phase Protection Element 50P
- Instantaneous Ground Protection Element 50G
- Instantaneous Negative Sequence Protection Element 50Q
- Instantaneous Under/Over Voltage Protection element 27/59

The *DigSILENT Pacific PowerFactory* model of the SEL701 contains the complete list of defined 17 generic curves.

## 2. PowerFactory Protection Functionality

The graphic below is the *PowerFactory Frame*. The *Frame* shows the *blocks* used in the *PowerFactory* model.

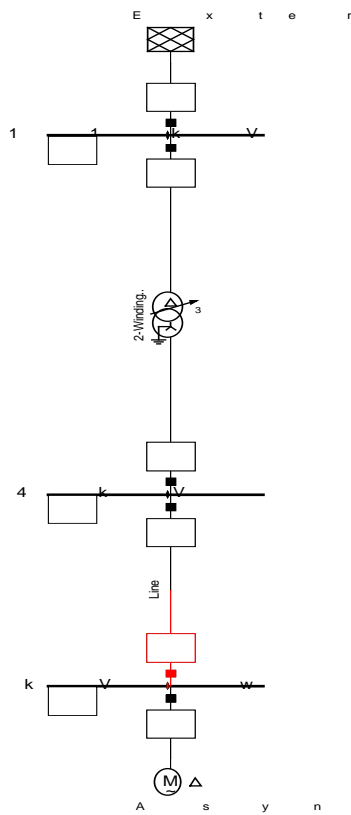
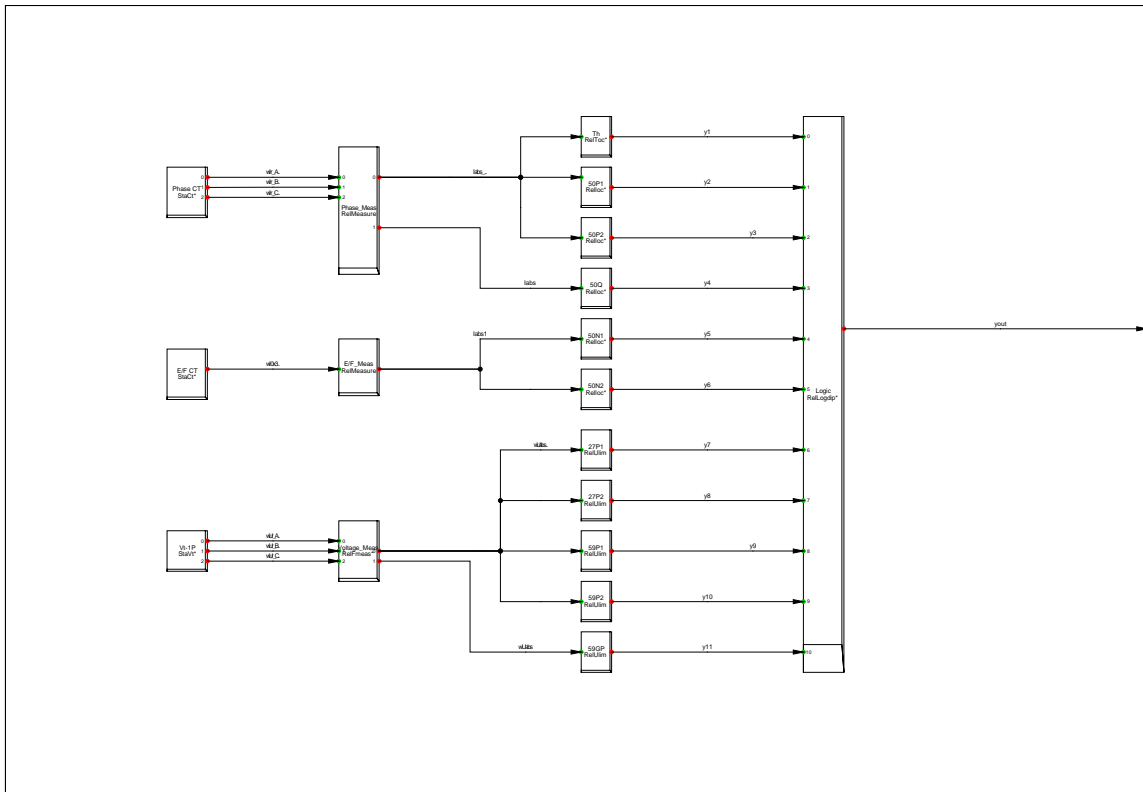


Figure 4 SEL701 PowerFactory Frame

SEL 701:



**Figure 5 Block diagram**

Each of the blocks modelled in the *PowerFactory Frame* (see Figure 5) represents one function of the relay, as follows;

### Protection Measurement Transformer Blocks

- The CT block requires a CT ratio of 200/1.
- The VT block requires a VT ratio of 4000/240

### Measurement Blocks

- Measurement Sequence / Phase: Nominal current and Nominal Voltage are set to 1A.
- Measurement Voltage Frequency: *Nominal Voltage* is set to 240V.

### Time Overcurrent Protection Blocks(49)

The Time Overcurrent (TOC) block allows the user to select *Characteristic*, *Time Dial*, *Time Adder* and the *Min Response Time*. All Protection Curves have a maximum current multiplier of 30p.u.

- Phase / Earth / Negative Sequence: *Pickup Current* has a range from 0.2-1.6A.

### Instantaneous Overcurrent Protection Setting blocks

Instantaneous Overcurrent (IOC) protection is only available for Phase, NPS and Earth Protection. IOC blocks are also used to represent Sensitive Ground Protection which operates with a definite time characteristic. The IOC block allows the user to select the *Pickup Current* and *Time Setting*. The IOC protection can be set with a time delay if required. The IOC *Time Setting* is the same value as used in the TOC blocks from the *Min Response Time*.

- Phase / Earth / Negative Sequence Trip IOC 1-4: *Pickup Current* has a range from 0.05-20A. *Time Setting* range is 0-400s.

### Voltage Protection

- Over Voltage /Under Voltage: *Pickup voltage* range is from 1-300p.u.

# APPENDIX E

## LOAD FLOW CALCULATION

## SHORT CURRENT CALCULATION

**Table 6 Load flow calculation in the MV Motor**

Murdoch Course	School of Engineering and Energy Electrical Power, Instrumentation and Control Engineering Calculation by Sungmin Cho				DIGSILENT PowerFactory 14.0.515	Project: Thesis Date: 1/11/2010				
Load Flow Calculation					Complete System Report: Substations, Voltage Profiles, Grid Interchange					
AC Load Flow, balanced, positive sequence					Automatic Model Adaptation for Convergency					
Automatic Tap Adjust of Transformers					No	Max. Acceptable Load Flow Error for				
Consider Reactive Power Limits					No	Nodes				
					Model Equations					
					Yes					
					1.00 kVA					
					0.10 %					
Grid: Grid		System Stage: Grid			Study Case: MV Motor				Annex: / 1	
rated Voltage [kV]	Bus-voltage [p.u.]	Bus-voltage [kV]	Angle [deg]	Active Power [MW]	Reactive Power [Mvar]	Power Factor [-]	Current [kA]	Loading [%]	Additional Data	
11kV										
Cub_2	/Xnet	External Grid		1.16	0.78	0.83	0.07	90.75	Sk":	10.00 MVA
Cub_3	/Tr2	2-Winding Transfor		1.16	0.78	0.83	0.07	90.75	Tap:	3.00 Min: 1 Max: 5
4kV with relay										
Cub_3	/Asm	0.97	3.88	28.15	1.12	0.69	0.85	0.20	95.91	Slip: 2.08 % xm: 5.60 p.u.
Cub_1	/Lne	Line		-1.12	-0.69	-0.85	0.20	97.90	Pv:	40.24 kW cLod: 0.00 Mvar L: 0.50 km
4kV										
Cub_1	/Tr2	2-Winding Transfor		-1.16	-0.70	-0.86	0.20	90.75	Tap:	3.00 Min: 1 Max: 5
Cub_2	/Lne	Line		1.16	0.70	0.86	0.20	97.90	Pv:	40.24 kW cLod: 0.00 Mvar L: 0.50 km



**Table 7 Load flow calculation in the LV Motor**

Murdoch Course	School of Engineering and Energy Electrical Power, Instrumentation and Control Engineering Calculation by Sungmin Cho				DIGSILENT PowerFactory 14.0.515	Project: Thesis Date: 1/11/2010			
Load Flow Calculation					Complete System Report: Substations, Voltage Profiles, Grid Interchange				
AC Load Flow, balanced, positive sequence				Automatic Model Adaptation for Convergency				Yes	
Automatic Tap Adjust of Transformers				Max. Acceptable Load Flow Error for				1.00 kVA	
Consider Reactive Power Limits				Model Equations				0.10 %	
Grid: Grid		System Stage: Grid			Study Case: LV Motor			Annex: / 1	
rated Voltage [kV]	Bus-voltage [p.u.]	Bus-voltage [kV]	deg	Active Power [MW]	Reactive Power [Mvar]	Power Factor [-]	Current [kA]	Loading [%]	Additional Data
11kV									
Cub_1	/Xnet	External Grid		0.03	0.02	0.80	0.00		Sk": 0.40 MVA
Cub_2	/Tr2	2-Winding Transfor		0.03	0.02	0.80	0.00	3.76	Tap: 0.00 Min: 0 Max: 0
0.46kV Terminal									
Cub_3	/Asm	LV Motor		0.03	0.02	0.80	0.05	94.82	Slip: 0.79 % xm: 1.79 p.u.
Cub_1	/Lne	Line		-0.03	-0.02	-0.80	0.05	38.63	Pv: 0.15 kW cLod: 0.00 Mvar L: 0.03 km
0.46kV									
Cub_1	/Tr2	2-Winding Transfor		-0.03	-0.02	-0.80	0.05	3.76	Tap: 0.00 Min: 0 Max: 0
Cub_2	/Lne	Line		0.03	0.02	0.80	0.05	38.63	Pv: 0.15 kW cLod: 0.00 Mvar L: 0.03 km

**Table 8 Short-Circuit Calculation of LV Motor : Single Phase to Ground Fault on Bus with Relay**

Murdoch Course	School of Engineering and Energy Electrical Power, Instrumentation and Control Engineering Calculation by Sungmin Cho	DIGSILENT PowerFactory 14.0.515	Project: Thesis Date: 1/11/2010
Relays Detailed Short-Circuit Calculation according to IEC60909			
		Single Phase to Ground / Max. Short-Circuit Currents	
Asynchronous Motors Always Considered	Grid Identification Automatic  Conductor Temperature User Defined	No	Short-Circuit Duration Break Time 0.10 s Fault Clearing Time (Ith) 1.00 s c-Voltage Factor User Defined No
Grid: Grid	System Stage: Grid	Study Case: LV Motor	Annex: / 1
SEL 701 Phase CTPhase CT	Relay Type : SEL701 Location : Busbar Branch : Line	: 0.46kV with Relay / : :	Ratio : 50A/1A Connection : Y
E/F CT: E/F CT	Location : Busbar Branch : Line	: 0.46kV with Relay / : :	Ratio : 50A/1A Connection : Y
Vt-1P : VT	Location : Busbar Branch : Line	: 0.46kV with Relay / : :	Ratio : 460V/120V Connection : Y - Y
50P1 : 50P1	( IEC: I>> ANSI: 50 )	Current [sec.A]	[pri.A] Tripping Time
Pickup Current : 9.080 sec.A	454.00 pri.A 9.080 p.u.	A : 6.338	316.91 <b>9999.999 s</b>
Time Setting : 0.050 s		B : 2.835	141.76
Total Time : 0.070 s		C : 2.835	141.76
50N1 : 50N1	( IEC: IE>> ANSI: 50N )	Current [sec.A]	[pri.A] Tripping Time
Pickup Current : 0.500 sec.A	25.00 pri.A 0.500 p.u.	12.009	600.43 <b>0.040 s</b>
Time Setting : 0.020 s			
Total Time : 0.040 s			
Th : Th	( IEC: I>t ANSI: 51 )	Current [sec.A]	[pri.A] Tripping Time
Current Setting : 1.000 sec.A	50.00 pri.A 1.000 p.u.	A : 6.338	316.91 <b>33.627 s</b>
Time Dial : 1.000	Time Shift : 1.000	B : 2.835	141.76
Characteristic : C15		C : 2.835	141.76

**Table 9 Short-Circuit Calculation of MV Motor : Single Phase to Ground fault on Bus with Relay**

Murdoch Course	School of Engineering and Energy Electrical Power, Instrumentation and Control Engineering Calculation by Sungmin Cho	DIGSILENT PowerFactory 14.0.515	Project: Thesis Date: 1/11/2010
Relays Detailed Short-Circuit Calculation according to IEC60909			
Asynchronous Motors Always Considered		Grid Identification Automatic  Conductor Temperature User Defined	Short-Circuit Duration Break Time 1.00 s Fault Clearing Time (Ith) 5.00 s c-Voltage Factor User Defined No
Grid: Grid	System Stage: Grid	Study Case: MV Motor	Annex: / 1
SEL 701 Phase CTPhase CT	Relay Type : SEL 701 Location : Busbar Branch : Line	: 4kV with relay / : :	Ratio : 200A/1A Connection : Y
E/F CT: E/F CT	Location : Busbar Branch : Line	: 4kV with relay / : :	Ratio : 200A/1A Connection : Y
Vt-1P : VT	Location : Busbar Branch : Line	: 4kV with relay / : :	Ratio : 4000V/240V Connection : Y - Y
50P1 : 50P1	( IEC: I>> ANSI: 50 )	Current [sec.A]	Tripping Time
Pickup Current : 10.180 sec.A	2036.00 pri.A 10.180 p.u.	A : 7.079	1415.73
Time Setting : 0.100 s		B : 2.284	456.86
Total Time : 0.120 s		C : 2.284	456.86
50N1 : 50N1	( IEC: IE>> ANSI: 50 )	Current [sec.A]	Tripping Time
Pickup Current : 0.500 sec.A	100.00 pri.A 0.500 p.u.	11.638	2327.50
Time Setting : 0.500 s			<u>0.510 s</u>
Total Time : 0.510 s			
Th : Th	( IEC: I>t ANSI: 51 )	Current [sec.A]	Tripping Time
Current Setting : 1.000 sec.A	200.00 pri.A 1.000 p.u.	A : 7.079	1415.73
Time Dial : 1.000	Time Shift : 1.000	B : 2.284	456.86
Characteristic : C4		C : 2.284	456.86

# APPENDIX F

## RESULT OF ON-LINE TEST IN THE LV MOTOR

### OFF LINE TEST

### STEADY STATE TEST

### DYNAMIC TEST

1. Off-line test

1) Thermal Protection Element (49)

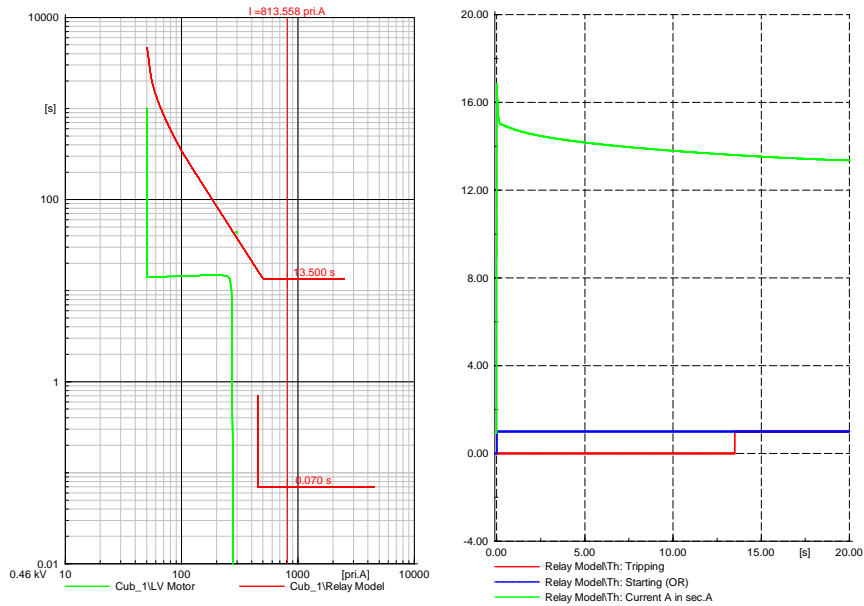


Figure 6 Time – overcurrent plot with single phase to ground fault on the bus

2) Instantaneous Protection Element (50P and 50N)

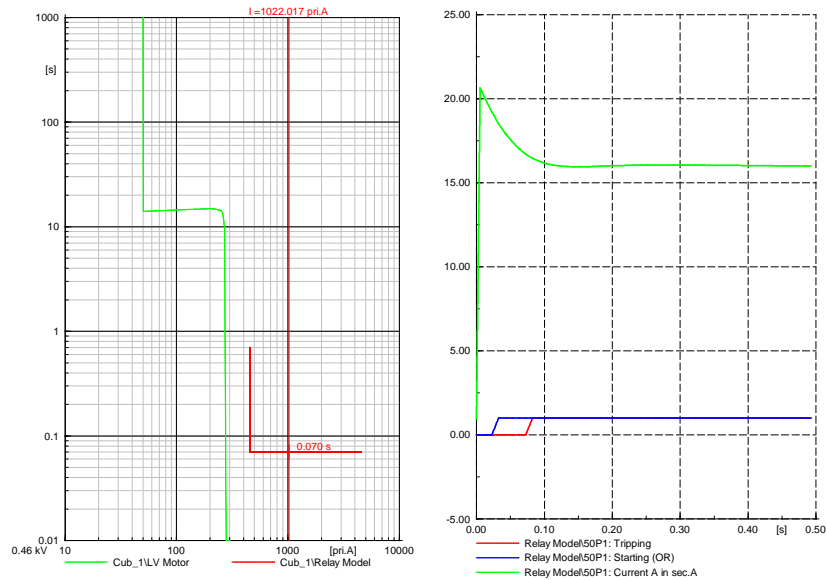


Figure 7 Time– overcurrent plot with two phases to ground fault on the bus (50P)

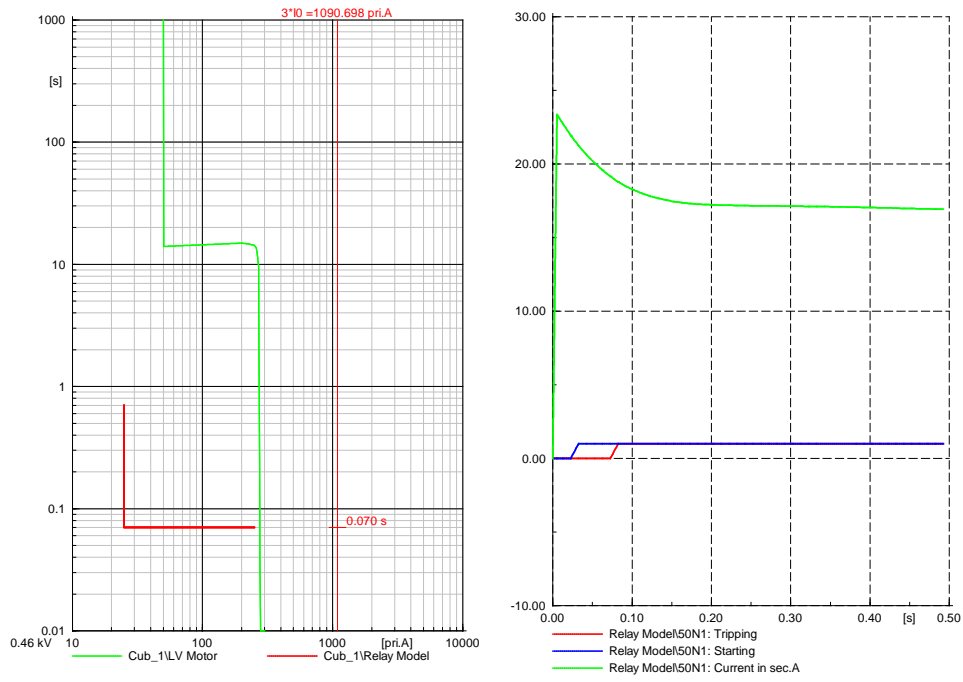


Figure 8 Time– overcurrent plot with single phase to ground fault on the bus (50G)

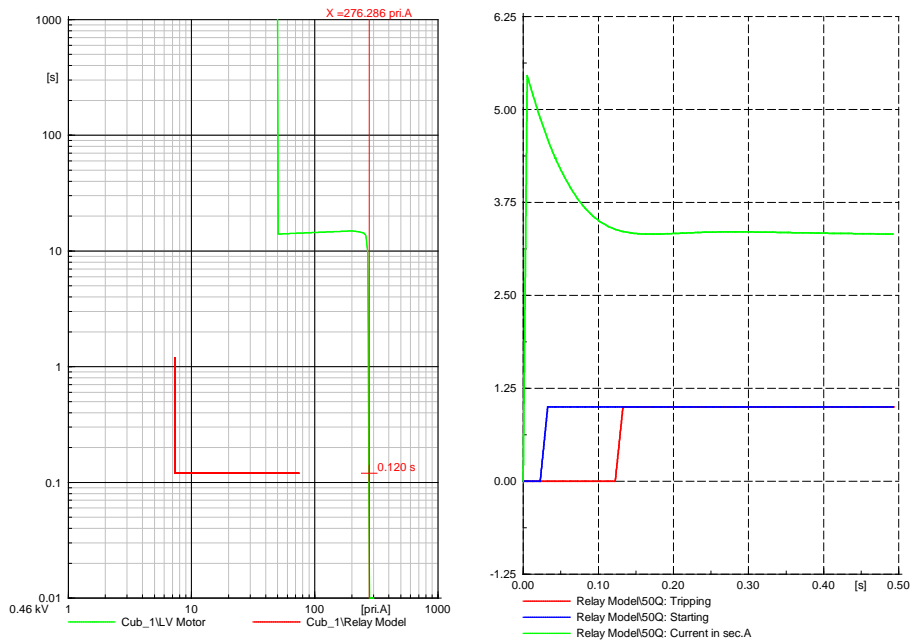


Figure 9 Time– overcurrent plot with two phase to ground fault on the bus (50Q)

2. On-line - Steady state test

1) Thermal Protection Element (49)

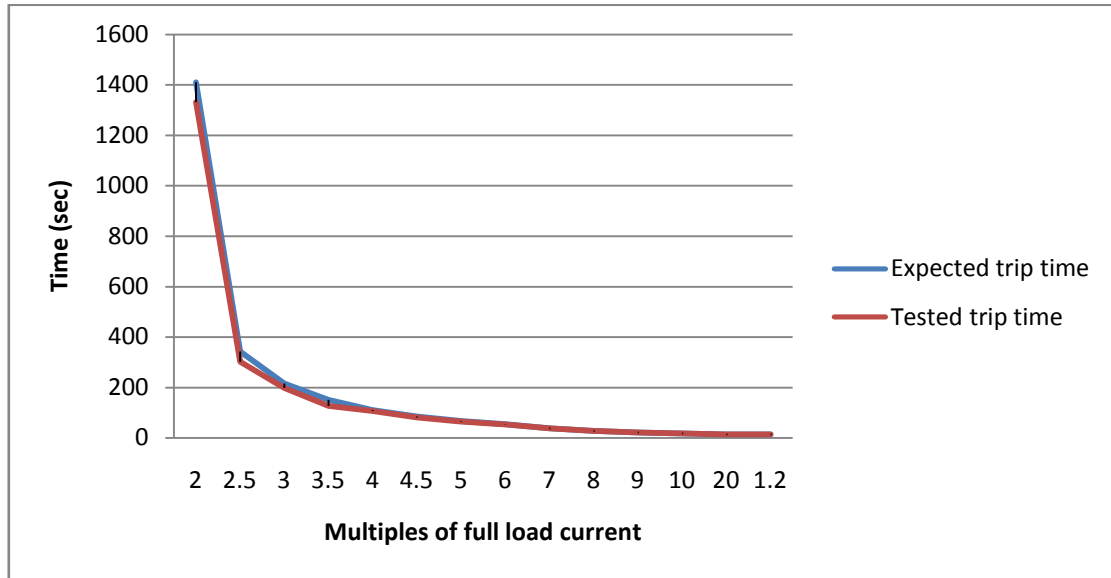


Figure 10 Plot of trip time versus multiples of full load current (curve 4 for LV motor)

Table 10 Test sheet of the thermal curve 4 for LV motor

Multiples of Full Load Amps	Expected tripping time(s) from data sheet	Tested Trip Value(s)	Error (%)
<b>0.95</b>	<b>Non</b>	<b>Non</b>	<b>0%</b>
1.2	1410.1	1331	-6%
2	342.1	301.12	-12%
2.5	216	197.34	-9%
3	150	126.8	-15%
3.5	110.2	105.64	-4%
4	84.4	81.27	-4%
4.5	66.7	63.67	-5%
5	54	53.04	-2%
6	37.5	37.6	0%
7	27.6	27.63	0%
8	21.1	21.15	0%
9	16.7	16.77	0%
10	13.5	13.5	0%
<b>20</b>	<b>13.5</b>	<b>13.5</b>	<b>0%</b>
		Total	4%

**Table 11 Test sheet of the instantaneous phase protection (50P) for LV motor**

Multiples of Full Load Amps	Expected tripping time(s) from data sheet	Tested Trip Value(s)	Error (%)
7	Non	Non	0%
8	Non	Non	0%
<b>9.534</b>	<b>0.1</b>	<b>0.1</b>	<b>0%</b>
15	0.1	0.1	0%
<b>20.44</b>	<b>0.1</b>	<b>0.1</b>	<b>0%</b>
		Total	0%

**Table 12 Test sheet of the instantaneous E/F protection (50N) for MV motor**

Multiples of Full Load Amps	Expected tripping time(s) from data sheet	Tested Trip Value(s)	Error (%)
0.1	Non	Non	0%
0.3	Non	Non	0%
<b>0.525</b>	<b>0.05</b>	<b>0.05</b>	<b>0%</b>
2	0.05	0.05	0%
<b>21.8</b>	<b>0.05</b>	<b>0.05</b>	<b>0%</b>
		Total	0%



1. On-line - Dynamic test

1) Instantaneous phase protection(50P)

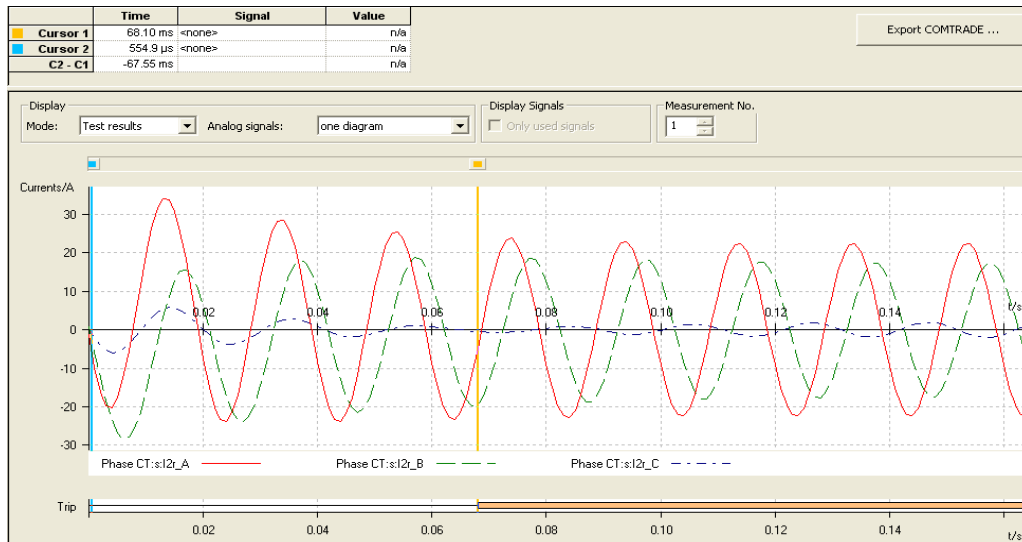


Figure 11 Test result of instantaneous phase element (50P) with two phases to ground fault

2) Instantaneous E/F protection(50N)

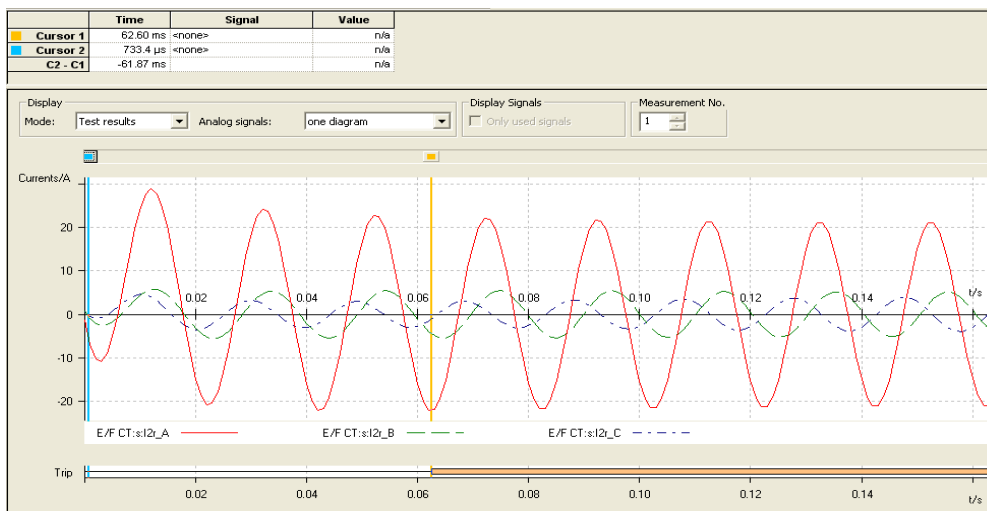


Figure 12 Test result of instantaneous phase element (50G) with single phases to ground fault

### 3) Instantaneous negative sequence protection(50Q)

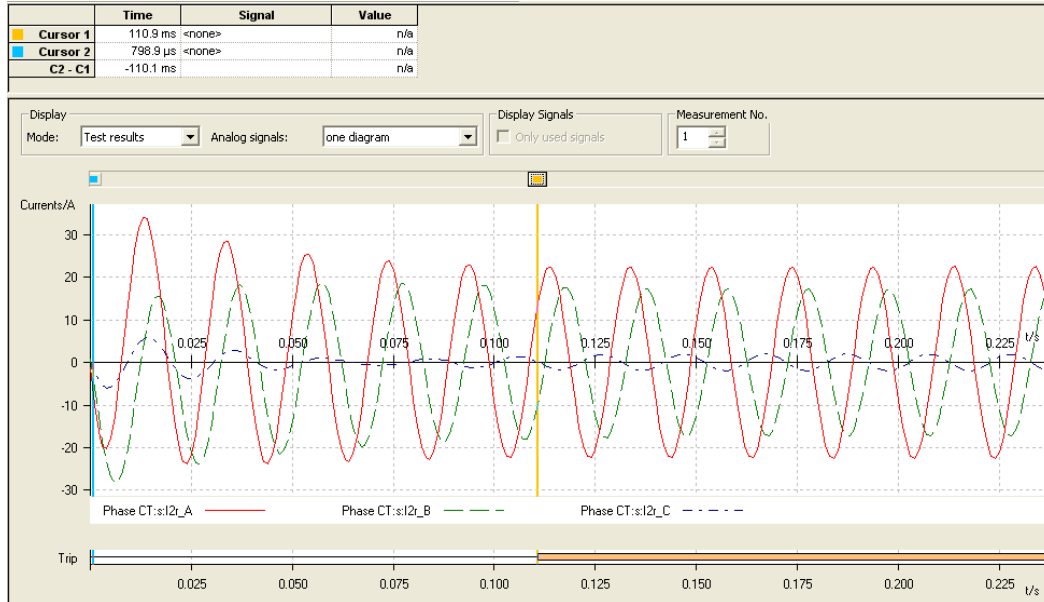


Figure 13 Test result of instantaneous phase element (50Q) with two phases to ground fault







